Integral Horsepower
AC Induction Motors
ODP, WPI Enclosures
TENV, TEAO, TEFC Enclosure
Explosion Proof
Any trademarks used in this manual are the property of their respective owners.

**Important:**
Be sure to check [www.baldor.com](http://www.baldor.com) to download the latest version of this manual in Adobe Acrobat PDF format.
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Section 1

General Information

Overview
This manual contains general procedures that apply to Baldor Motor products. Be sure to read and understand the Safety Notice statements in this manual. For your protection, do not install, operate or attempt to perform maintenance procedures until you understand the Warning and Caution statements.

A Warning statement indicates a possible unsafe condition that can cause harm to personnel.
A Caution statement indicates a condition that can cause damage to equipment.

Important:
This instruction manual is not intended to include a comprehensive listing of all details for all procedures required for installation, operation and maintenance. This manual describes general guidelines that apply to most of the motor products shipped by Baldor. If you have a question about a procedure or are uncertain about any detail, Do Not Proceed. Please contact your Baldor distributor for more information or clarification.

Before you install, operate or perform maintenance, become familiar with the following:

- IEC 34−1 Electrical and IEC72−1 Mechanical specifications
- ANSI C51.5, the National Electrical Code (NEC) and local codes and practices.

Limited Warranty
www.baldor.com/support/warranty_standard.asp

Safety Notice:
This equipment contains high voltage! Electrical shock can cause serious or fatal injury. Only qualified personnel should attempt installation, operation and maintenance of electrical equipment. Be sure that you are completely familiar with NEMA publication MG-2, safety standards for construction and guide for selection, installation and use of electric motors and generators, the National Electrical Code and local codes and practices. Unsafe installation or use can cause conditions that lead to serious or fatal injury. Only qualified personnel should attempt the installation, operation and maintenance of this equipment.

WARNING:
Do not touch electrical connections before you first ensure that power has been disconnected. Electrical shock can cause serious or fatal injury. Only qualified personnel should attempt the installation, operation and maintenance of this equipment.

WARNING:
Disconnect all electrical power from the motor windings and accessory devices before disassembly of the motor. Electrical shock can cause serious or fatal injury.

WARNING:
Be sure the system is properly grounded before applying power. Do not apply AC power before you ensure that all grounding instructions have been followed. Electrical shock can cause serious or fatal injury. National Electrical Code and Local codes must be carefully followed.

WARNING:
Avoid extended exposure to machinery with high noise levels. Be sure to wear ear protective devices to reduce harmful effects to your hearing.

WARNING:
Surface temperatures of motor enclosures may reach temperatures which can cause discomfort or injury to personnel accidentally coming into contact with hot surfaces. When installing, protection should be provided by the user to protect against accidental contact with hot surfaces. Failure to observe this precaution could result in bodily injury.

WARNING:
This equipment may be connected to other machinery that has rotating parts or parts that are driven by this equipment. Improper use can cause serious or fatal injury. Only qualified personnel should attempt to install operate or maintain this equipment.

WARNING:
Do not by-pass or disable protective devices or safety guards. Safety features are designed to prevent damage to personnel or equipment. These devices can only provide protection if they remain operative.

WARNING:
Avoid the use of automatic reset devices if the automatic restarting of equipment can be hazardous to personnel or equipment.

WARNING:
Be sure the load is properly coupled to the motor shaft before applying power. The shaft key must be fully captive by the load device. Improper coupling can cause harm to personnel or equipment if the load decouples from the shaft during operation.

WARNING:
UL Listed motors must only be serviced by UL Approved Authorized Baldor Service Centers if these motors are to be returned to a hazardous and/or explosive atmosphere.

WARNING:
Thermostat contacts automatically reset when the motor has slightly cooled down. To prevent injury or damage, the control circuit should be designed so that automatic starting of the motor is not possible when the thermostat resets.

WARNING:
Use proper care and procedures that are safe during handling, lifting, installing, operating and maintaining operations. Improper methods may cause muscle strain or other harm.

WARNING:
Pacemaker danger – Magnetic and electromagnetic fields in the vicinity of current carrying carrying conductors and permanent magnet motors can result result in a serious health hazard to persons with cardiac pacemakers, metal implants, and hearing aids. To avoid risk, stay way from the area surrounding a permanent magnet motor.

WARNING:
Before performing any motor maintenance procedure, be sure that the equipment connected to the motor shaft cannot cause shaft rotation. If the load can cause shaft rotation, disconnect the load from the motor shaft before maintenance is performed. Unexpected mechanical rotation of the motor parts can cause injury or motor damage.

Continued on next page.
**Safety Notice Continued**

**WARNING:** Do not use non UL/CSA listed explosion proof motors in the presence of flammable or combustible vapors or dust. These motors are not designed for atmospheric conditions that require explosion proof operation.

**WARNING:** Motors that are to be used in flammable and/or explosive atmospheres must display the UL label on the nameplate along with CSA listed logo. Specific service conditions for these motors are defined in NFPA 70 (NEC) Article 500.

**WARNING:** Guards must be installed for rotating parts such as couplings, pulleys, external fans, and unused shaft extensions, should be permanently guarded to prevent accidental contact by personnel. Accidental contact with body parts or clothing can cause serious or fatal injury.

**Caution:** To prevent premature equipment failure or damage, only qualified maintenance personnel should perform maintenance.

**Caution:** Do not over tension belts. Excess tension may damage the motor or driven equipment.

**Caution:** Do not over-lubricate motor as this may cause premature bearing failure.

**Caution:** Do not lift the motor and its driven load by the motor lifting hardware. The motor lifting hardware is adequate for lifting only the motor. Disconnect the load (gears, pumps, compressors, or other driven equipment) from the motor shaft before lifting the motor.

**Caution:** If eye bolts are used for lifting a motor, be sure they are securely tightened. The lifting direction should not exceed a 20 ° angle from the shank of the eye bolt or lifting lug. Excessive lifting angles can cause damage.

**Caution:** To prevent equipment damage, be sure that the electrical service is not capable of delivering more than the maximum motor rated amps listed on the rating plate.

**Caution:** If a HI POT test (High Potential Insulation test) must be performed, follow the precautions and procedure in NEMA MG1 and MG2 standards to avoid equipment damage.

**Caution:** The space heaters are designed to operate at or below the maximum surface temperature stated on the nameplate. If the marked ambient and/or voltage are exceeded this maximum surface temperature can be exceeded and can damage the motor windings. If applied in a division 2 or zone 2 environment this excessive temperature may cause ignition of hazardous materials.

**Caution:** Shaker Duty motors must be properly lubricated prior to Start Up to prevent damage. See Section 3.

If you have any questions or are uncertain about any statement or procedure, or if you require additional information please contact your Baldor distributor or an Authorized Baldor Service Center.

**Receiving**

Each Baldor Electric Motor is thoroughly tested at the factory and carefully packaged for shipment. When you receive your motor, there are several things you should do immediately.

1. Observe the condition of the shipping container and report any damage immediately to the commercial carrier that delivered your motor.
2. Verify that the part number of the motor you received is the same as the part number listed on your purchase order.

**Handling**

The motor should be lifted using the lifting lugs or eye bolts provided.

**Caution:** Do not lift the motor and its driven load by the motor lifting hardware. The motor lifting hardware is adequate for lifting only the motor. Disconnect the load (gears, pumps, compressors, or other driven equipment) from the motor shaft before lifting the motor.

1. Use the lugs or eye bolts provided to lift the motor. Never attempt to lift the motor and additional equipment connected to the motor by this method. The lugs or eye bolts provided are designed to lift only the motor. Never lift the motor by the motor shaft or the hood of a WPII motor.
2. To avoid condensation inside the motor, do not unpack until the motor has reached room temperature. (Room temperature is the temperature of the room in which it will be installed). The packing provides insulation from temperature changes during transportation.
3. When lifting a WPII (Weather Proof Type 2) motor, do not lift the motor by inserting lifting lugs into holes on top of the cooling hood. These lugs are to be used for hood removal only. A spreader bar should be used to lift the motor by the cast lifting lugs located on the motor frame.
4. If the motor must be mounted to a plate with the driven equipment such as pump, compressor etc., it may not be possible to lift the motor alone. For this case, the assembly should be lifted by a sling around the mounting base. The entire assembly can be lifted as an assembly for installation. Do not lift the assembly using the motor lugs or eye bolts provided. Lugs or eye bolts are designed to lift motor only. If the load is unbalanced (as with couplings or additional attachments) additional slings or other means must be used to prevent tipping. In any event, the load must be secure before lifting. If the load is unbalanced (as with couplings or additional attachments) additional slings or other means must be used to prevent tipping. In any event, the load must be secure before lifting.
Storage

Storage requirements for motors and generators that will not be placed in service for at least six months from date of shipment.

Improper motor storage will result in seriously reduced reliability and failure. An electric motor that does not experience regular usage while being exposed to normally humid atmospheric conditions is likely to develop rust in the bearings or rust particles from surrounding surfaces may contaminate the bearings. The electrical insulation may absorb an excessive amount of moisture leading to the motor winding failure.

A wooden crate “shell” should be constructed to secure the motor during storage. This is similar to an export box but the sides & top must be secured to the wooden base with lag bolts (not nailed as export boxes are) to allow opening and reclosing many times without damage to the “shell”.

Minimum resistance of motor winding insulation is 5 Meg ohms or the calculated minimum, which ever is greater. Minimum resistance is calculated as follows: \[ R_m = kV + 1 \]

where: \( R_m \) is minimum resistance to ground in Meg–Ohms and \( kV \) is rated nameplate voltage defined as Kilo–Volts.)

Example: For a 480VAC rated motor \( R_m = 1.48 \) meg–ohms (use 5 M \( \Omega \)).

For a 4160VAC rated motor \( R_m = 5.16 \) meg–ohms.

Preparation for Storage

1. Some motors have a shipping brace attached to the shaft to prevent damage during transportation. The shipping brace, if provided, must be removed and stored for future use. The brace must be reinstalled to hold the shaft firmly in place against the bearing before the motor is moved.

2. Store in a clean, dry, protected warehouse where control is maintained as follows:
   a. Shock or vibration must not exceed 2 mils peak-to-peak maximum at 60 hertz, to prevent the bearings from brinelling. If shock or vibration exceeds this limit vibration isolation pads must be used.
   b. Storage temperatures of 10 ºC (50 ºF) to 49 ºC (120 ºF) must be maintained.
   c. Relative humidity must not exceed 60%.
   d. Motor space heaters (when present) are to be connected and energized whenever there is a possibility that the storage ambient conditions will reach the dew point. Space heaters are optional.

Note: Remove motor from containers when heaters are energized, reprotect if necessary.

3. Measure and record the resistance of the winding insulation (dielectric withstand) every 30 days of storage.
   a. If motor insulation resistance decreases below the minimum resistance, contact your Baldor District office.
   b. Place new desiccant inside the vapor bag and re–seal by taping it closed.
   c. If a zipper–closing type bag is used instead of the heat–sealed type bag, zip the bag closed instead of taping it. Be sure to place new desiccant inside bag after each monthly inspection.
   d. Place the shell over the motor and secure with lag bolts.

4. Where motors are mounted to machinery, the mounting must be such that the drains and breathers are fully operable and are at the lowest point of the motor. Vertical motors must be stored in the vertical position. Storage environment must be maintained as stated in step 2.

5. Motors with anti–friction bearings are to be greased at the time of going into extended storage with periodic service as follows:
   a. Motors marked “Do Not Lubricate” on the nameplate do not need to be greased before or during storage.
   b. Ball and roller bearing (anti–friction) motor shafts are to be rotated manually every 3 months and greased every 6 months in accordance with the Maintenance section of this manual.
   c. Sleeve bearing (oil lube) motors are drained of oil prior to shipment. The oil reservoirs must be refilled to the indicated level with the specified lubricant, (see Maintenance). The shaft should be rotated monthly by hand at least 10 to 15 revolutions to distribute oil to bearing surfaces.
   d. “Provisions for oil mist lubrication” – These motors are packed with grease. Storage procedures are the same as paragraph 5b.
   e. “Oil Mist Lubricated” – These bearings are protected for temporary storage by a corrosion inhibitor. If stored for greater than 3 months or outdoor storage is anticipated, connected to the oil mist system while in storage. If this is not possible, add the amount of grease indicated under “Standard Condition” in Section 3, then rotate the shaft 15 times by hand.
6. All breather drains are to be fully operable while in storage (drain plugs removed). The motors must be stored so that the drain is at the lowest point. All breathers and automatic “T” drains must be operable to allow breathing and draining at points other than through the bearings around the shaft. Vertical motors should be stored in a safe stable vertical position.

7. Coat all external machined surfaces with a rust preventing material. An acceptable product for this purpose is Exxon Rust Ban # 392.

8. Carbon brushes should be lifted and held in place in the holders, above the commutator, by the brush holder fingers. The commutator should be wrapped with a suitable material such as cardboard paper as a mechanical protection against damage.

Non−Regreaseable Motors

Non−regreaseable motors with “Do Not Lubricate” on the nameplate should have the motor shaft rotated 15 times to redistribute the grease within the bearing every 3 months or more often.

All Other Motor Types

Before storage, the following procedure must be performed.

1. Remove the grease drain plug, if supplied, (opposite the grease fitting) on the bottom of each bracket prior to lubricating the motor.
2. The motor with regreasable bearing must be greased as instructed in Section 3 of this manual.
3. Replace the grease drain plug after greasing.
4. The motor shaft must be rotated a minimum of 15 times after greasing.
5. Motor Shafts are to be rotated at least 15 revolutions manually every 3 months and additional grease added every nine months (see Section 3) to each bearing.
6. Bearings are to be greased at the time of removal from storage.

Removal From Storage

1. Remove all packing material.
2. Measure and record the electrical resistance of the winding insulation resistance meter at the time of removal from storage. The insulation resistance must not be less than 50% from the initial reading recorded when the motor was placed into storage. A decrease in resistance indicates moisture in the windings and necessitates electrical or mechanical drying before the motor can be placed into service. If resistance is low, contact your Baldor District office.
3. Regrease the bearings as instructed in Section 3 of this manual.
4. Reinstall the original shipping brace if motor is to be moved. This will hold the shaft firmly against the bearing and prevent damage during movement.
Equipment Marking for IEC Certified Product

IEC certified products have special markings that identify the protection concept and environment requirements. An example is shown in Figure 1-1.

**Figure 1-1 IEC Certified Product Markings**

![Diagram showing IEC certification markings]  
- **Ex Protection Concept (ExnA)**
- **Gas Group (IIC)**
- **Temperature Class**
- **Ambient Range**
- **ExnA MOTOR**
- **Gc Tamb**
- **ºC to ºC**
- **ATEX Equipment Group and Category (II3)**
- **Type of Atmosphere: G-Gas, D-Dust (G)**
- **European Conformity Mark**
- **Place of Manufacture**

**Specific Conditions of Use:**

If the motor certificate number is followed by the symbol “X”, this indicates that the motor has specific conditions of use which are indicated on the certificate. It is necessary to review the product certification certificate in conjunction with this instruction manual.

**Operation On Frequency Converters:**

If the motor is evaluated for operation with an adjustable speed drive, the type of converter (for example PWM for Pulse Width Modulated) and safe speed ranges (for example 0-120Hz) will be specified in the certification documents or on motor nameplates. It is necessary to consult the adjustable speed drive manual for proper setup. IECEx Certificates are available online at www.iecex.com

<table>
<thead>
<tr>
<th>Unit Conversions</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Inches to Millimeters</strong></td>
</tr>
<tr>
<td>Inches x 25.4 = mm</td>
</tr>
<tr>
<td><strong>Millimeters to Inches</strong></td>
</tr>
<tr>
<td>mm x .03937 = Inches</td>
</tr>
<tr>
<td><strong>Horsepower to Kilowatts</strong></td>
</tr>
<tr>
<td>Hp x .746 = Kw</td>
</tr>
<tr>
<td><strong>Kilowatts to Horsepower</strong></td>
</tr>
<tr>
<td>Kw x 1.341 = Hp</td>
</tr>
<tr>
<td><strong>Pounds to Kilograms</strong></td>
</tr>
<tr>
<td>Lbs x .454 = Kg</td>
</tr>
<tr>
<td><strong>Kilograms to Pounds</strong></td>
</tr>
<tr>
<td>Kg x 2.205 = Lbs</td>
</tr>
</tbody>
</table>

Typical Speed vs Torque Curves are shown in Figure 1-2. For values relative to your specific motor, consult the motor nameplate marking.
EMC Compliance Statement for European Union

The motors described in this instruction manual are designed to comply 2014/30/EU. These motors are commercial in design and not intended for residential use. When used with converters, please consult converter manufacturers literature regarding recommendations on cable types, cable shielding, cable shielding termination, connection recommendations and any filters which may be recommended for EMC compliance. For additional information, consult Baldor MN1383.
Section 2
Installation & Operation

Overview
Installation should conform to the National Electrical Code as well as local codes and practices. When other devices are coupled to the motor shaft, be sure to install protective devices to prevent future accidents. Some protective devices include, coupling, belt guard, chain guard, shaft covers etc. These protect against accidental contact with moving parts. Machinery that is accessible to personnel should provide further protection in the form of guard rails, screening, warning signs etc.

Location
It is important that motors be installed in locations that are compatible with motor enclosure and ambient conditions. Improper selection of the motor enclosure and ambient conditions can lead to reduced operating life of the motor.

For Group I Mining Motors where breather drains are used specified, Breather drain shall be mounted or protected in installation such that it is guarded from direct impact.”

Proper ventilation for the motor must be provided. Obstructed airflow can lead to reduction of motor life.

1. **Open Drip-Proof/WPI** motors are intended for use indoors where atmosphere is relatively clean, dry, well ventilated and non-corrosive.

2. **Totally Enclosed and WPII** motors may be installed where dirt, moisture or dust are present and in outdoor locations.

**Severe Duty**, **IEEE 841** and Washdown Duty enclosed motors are designed for installations with high corrosion or excessive moisture conditions. These motors should not be placed into an environment where there is the presence of flammable or combustible vapors, dust or any combustible material, unless specifically designed for this type of service. **IEEE841** motors are suitable for application in Class I Division 2 and Class I Zone 2 areas on sine wave power in accordance with the applicable codes and standards.

**Hazardous Locations** are those where there is a risk of ignition or explosion due to the presence of combustible gases, vapors, dust, fibers, or flyings. Facilities requiring special equipment for hazardous locations are typically classified in accordance with local requirements. In the US market, guidance is provided by the National Electric Code.

**EMC Compliance Statement for European Union**
The motors described in this instruction manual are designed to comply 2014/30/EU. These motors are commercial in design and not intended for residential use.

Mounting Location
The motor should be installed in a location compatible with the motor enclosure and specific ambient. To allow adequate air flow, the following clearances must be maintained between the motor and any obstruction:

<table>
<thead>
<tr>
<th>Enclosure Type</th>
<th>Clearances</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>TEFC / TENV</strong> (IC0141) Enclosures</td>
<td>Fan Cover Air Intake 180 – 210T Frame 1” (25mm)</td>
</tr>
<tr>
<td></td>
<td>Fan Cover Air Intake 250 – 449T Frame 4” (100mm)</td>
</tr>
<tr>
<td></td>
<td>IEC 112 – 132 1” (25mm)</td>
</tr>
<tr>
<td></td>
<td>IEC 160 – 280 4” (100mm)</td>
</tr>
<tr>
<td></td>
<td>Exhaust Envelope equal to the P Dimension on the motor dimension sheet</td>
</tr>
<tr>
<td>OPEN/Protected Enclosures</td>
<td>Bracket Intake Same as TEFC</td>
</tr>
<tr>
<td></td>
<td>Frame Exhaust Exhaust out the sides envelope</td>
</tr>
<tr>
<td></td>
<td>A minimum of the P dimension plus 2” (50mm)</td>
</tr>
<tr>
<td></td>
<td>Exhaust out the end same as intake.</td>
</tr>
</tbody>
</table>

The motor must be securely installed to a rigid foundation or mounting surface to minimize vibration and maintain alignment between the motor and shaft load. Failure to provide a proper mounting surface may cause vibration, misalignment and bearing damage.

Foundation caps and sole plates are designed to act as spacers for the equipment they support. If these devices are used, be sure that they are evenly supported by the foundation or mounting surface.

When installation is complete and accurate alignment of the motor and load is accomplished, the base should be grouted to the foundation to maintain this alignment.

The standard motor base is designed for horizontal or vertical mounting. Adjustable or sliding rails are designed for horizontal mounting only. Consult your Baldor distributor or authorized Baldor Service Center for further information.
Frame Mounting Holes

Some motors have standardized frames containing 6 or 8 mounting holes. 6 hole frames are not suitable for field reversal of mounting from F−1 to F−2, etc. Figure 2-1 indicates the proper mounting holes to use.

**Figure 2-1 6 & 8 Hole Motor Frame Mounting**

- **Caution:** Do not lift the motor and its driven load by the motor lifting hardware. The motor lifting hardware is adequate for lifting only the motor. Disconnect the load (gears, pumps, compressors, or other driven equipment) from the motor shaft before lifting the motor.

  In the case of assemblies on a common base, any lifting means provided on the motor should not be used to lift the assembly and base but, rather, the assembly should be lifted by a sling around the base or by other lifting means provided on the base. Assure lifting in the direction intended in the design of the lifting means. Likewise, precautions should be taken to prevent hazardous overloads due to deceleration, acceleration or shock forces.

**Alignment**

Accurate alignment of the motor with the driven equipment is extremely important. The pulley, sprocket, or gear used in the drive should be located on the shaft as close to the shaft shoulder as possible. It is recommended to heat the pulley, sprocket, or gear before installing on the motor shaft. Forcibly driving a unit on the motor shaft will damage the bearings.

1. **Direct Coupling**
   For direct drive, use flexible couplings if possible. Consult the drive or equipment manufacturer for more information. Mechanical vibration and roughness during operation may indicate poor alignment. Use dial indicators to check alignment. The space between coupling hubs should be maintained as recommended by the coupling manufacturer.

2. **End-Play Adjustment**
   The axial position of the motor frame with respect to its load is also extremely important. The standard motor bearings are not designed for excessive external axial thrust loads. Improper adjustment will cause failure.

3. **Pulley Ratio**
   The best practice is to not exceed an 8:1 pulley ratio.

**Caution:** Do not over tension belts. Excess tension may damage the motor or driven equipment.

4. **Belt Drive**
   Align sheaves carefully to minimize belt wear and axial bearing loads (see End-Play Adjustment). Belt tension should be sufficient to prevent belt slippage at rated speed and load. However, belt slippage may occur during starting.

**Doweling & Bolting**

After proper alignment is verified, dowel pins should be inserted through the motor feet into the foundation. This will maintain the correct motor position should motor removal be required. (Baldor®Reliance motors are designed for doweling.)

1. Drill dowel holes in diagonally opposite motor feet in the locations provided.
2. Drill corresponding holes in the foundation.
3. Ream all holes.
4. Install proper fitting dowels.
5. Mounting bolts must be carefully tightened to prevent changes in alignment.
Use a flat washer and lock washer under each nut or bolt head to hold the motor feet secure.

**WARNING:** Guards must be installed for rotating parts such as couplings, pulleys, external fans, and unused shaft extensions, should be permanently guarded to prevent accidental contact by personnel. Accidental contact with body parts or clothing can cause serious or fatal injury.

**Guards**

Guards must be installed for rotating parts such as couplings, pulleys, external fans, and unused shaft extensions. This is particularly important where the parts have surface irregularities such as keys, key ways or set screws. Some satisfactory methods of guarding are:

1. Covering the machine and associated rotating parts with structural or decorative parts of the driven equipment.
2. Providing covers for the rotating parts. Covers should be sufficiently rigid to maintain adequate guarding during normal service.

**Power Connection**

Motor and control wiring, overload protection, disconnects, accessories and grounding should conform to the National Electrical Code and local codes and practices.

For ExnA hazardous location motors, it is a specific condition of use that all terminations in a conduit box be fully insulated. Fully insulated and lugged terminations must be bolted and provided with lock washer to prevent rotation. Flying leads must be insulated with two full wraps of electrical grade insulating tape or heat shrink tubing.

**Grounding**

In the USA consult the National Electrical Code, Article 430 for information on grounding of motors and generators, and Article 250 for general information on grounding. In making the ground connection, the installer should make certain that there is a solid and permanent metallic connection between the ground point, the motor or generator terminal housing, and the motor or generator frame. In non-USA locations consult the appropriate national or local code applicable.

Motors with resilient cushion rings usually must be provided with a bonding conductor across the resilient member. Some motors are supplied with the bonding conductor on the concealed side of the cushion ring to protect the bond from damage. Motors with bonded cushion rings should usually be grounded at the time of installation in accordance with the above recommendations for making ground connections. When motors with bonded cushion rings are used in multimotor installations employing group fusing or group protection, the bonding of the cushion ring should be checked to determine that it is adequate for the rating of the branch circuit over current protective device being used.

There are applications where grounding the exterior parts of a motor or generator may result in greater hazard by increasing the possibility of a person in the area simultaneously contacting ground and some other nearby live electrical parts of other ungrounded electrical equipment. In portable equipment it is difficult to be sure that a positive ground connection is maintained as the equipment is moved, and providing a grounding conductor may lead to a false sense of security.

Select a motor starter and over current protection suitable for this motor and its application. Consult motor starter application data as well as the National Electric Code and/or other applicable local codes.

For motors installed in compliance with IEC requirements, the following minimum cross sectional area of the protective conductors should be used:

<table>
<thead>
<tr>
<th>Crosssectional area of phase conductors, S (mm²)</th>
<th>Minimum crosssectional area of the corresponding protective conductor, S_p (mm²)</th>
</tr>
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<tbody>
<tr>
<td>6</td>
<td>6</td>
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<td>10</td>
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<td>120</td>
<td>70</td>
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<tr>
<td>150</td>
<td>70</td>
</tr>
</tbody>
</table>

Equipotential bonding connection shall made using a conductor with a cross-sectional area of at least 4 mm².
Conduit Box

For ease of making connections, an oversize conduit box is provided. Most conduit boxes can be rotated 360 ° in 90 ° increments. Auxiliary conduit boxes are provided on some motors for accessories such as space heaters, RTD's etc.

AC Power

Motors with flying lead construction must be properly terminated and insulated.

Connect the motor leads as shown on the connection diagram located on the name plate or inside the cover on the conduit box. Be sure the following guidelines are met:

1. AC power is within ±10% of rated voltage with rated frequency. (See motor name plate for ratings).

   OR

2. AC power is within ±5% of rated frequency with rated voltage.

   OR

3. A combined variation in voltage and frequency of ±10% (sum of absolute values) of rated values, provided the frequency variation does not exceed ±5% of rated frequency.

Performance within these voltage and frequency variations are shown in Figure 2-3.

---

AC Power

Motors with flying lead construction must be properly terminated and insulated.

Connect the motor leads as shown on the connection diagram located on the name plate or inside the cover on the conduit box. Be sure the following guidelines are met:

1. AC power is within ±10% of rated voltage with rated frequency. (See motor name plate for ratings).

   OR

2. AC power is within ±5% of rated frequency with rated voltage.

   OR

3. A combined variation in voltage and frequency of ±10% (sum of absolute values) of rated values, provided the frequency variation does not exceed ±5% of rated frequency.

Performance within these voltage and frequency variations are shown in Figure 2-3.

---

Rotation

All three phase motors are reversible. To reverse the direction of rotation, disconnect and lock out power and interchange any two of the three line leads for three phase motors. For single phase motors, check the connection diagram to determine if the motor is reversible and follow the connection instructions for lead numbers to be interchanged. Not all single phase motors are reversible.

Adjustable Frequency Power Inverters used to supply adjustable frequency power to induction motors produce wave forms with lower order harmonics with voltage spikes superimposed. Turn-to-turn, phase-to-phase, and ground insulation of stator windings are subject to the resulting dielectric stresses. Suitable precautions should be taken in the design of these drive systems to minimize the magnitude of these voltage spikes. Consult the drive instructions for maximum acceptable motor lead lengths, and proper grounding.

Note: Main power leads for CE Marked Motors may be marked U,V,W – for standard configurations, please consult connection diagrams.

Caution:

The space heaters are designed to operate at or below the maximum surface temperature stated on the nameplate. If the marked ambient and/or voltage are exceeded this maximum surface temperature can be exceeded and can damage the motor windings. If applied in a division 2 or zone 2 environment this excessive temperature may cause ignition of hazardous materials.
Connection Diagrams

AC Motor Connection Diagram

IEC VERSUS NEMA LEAD MARKING
EXAMPLE COMPARISONS OF IEC AND NEMA LEAD MARKINGS FOR COMMON CONNECTION TYPES ARE SHOWN BELOW.

SINGLE PHASE MOTORS

<table>
<thead>
<tr>
<th>SINGLE VOLTAGE NON REVERSIBLE</th>
<th>SINGLE VOLTAGE REVERSIBLE</th>
</tr>
</thead>
<tbody>
<tr>
<td>U1(T1)</td>
<td>U1(T1)</td>
</tr>
<tr>
<td>U2(T4)</td>
<td>Z1(T6)</td>
</tr>
<tr>
<td>Z2(T5)</td>
<td>AUXILIARY WINDING</td>
</tr>
<tr>
<td>U2(T4)</td>
<td>MAIN WINDING</td>
</tr>
</tbody>
</table>

DUAL VOLTAGE REVERSIBLE

| U1(T1)                        | Z1(T6)                    |
| Z2(T5)                        | AUXILIARY WINDING         |
| U2(T2)                        | MAIN WINDING              |
| U3(T3)                        |                           |
| U4(T4)                        |                           |

AC Motor Connection Diagram

SIX LEADS

DELTA-WYE CONNECT

<table>
<thead>
<tr>
<th>U1(T1)</th>
<th>W2(T4)</th>
<th>V2(T5)</th>
</tr>
</thead>
<tbody>
<tr>
<td>W1(T3)</td>
<td>V1(T2)</td>
<td></td>
</tr>
</tbody>
</table>

WYE-DELTA CONNECT

<table>
<thead>
<tr>
<th>U1(T1)</th>
<th>W2(T6)</th>
<th>V2(T5)</th>
</tr>
</thead>
<tbody>
<tr>
<td>W1(T3)</td>
<td>V1(T2)</td>
<td></td>
</tr>
</tbody>
</table>

DUAL VOLTAGE HIGH TO LOW VOLTAGE RATIO 1:3:1

<table>
<thead>
<tr>
<th>W2(T4)</th>
<th>V2(T5)</th>
</tr>
</thead>
<tbody>
<tr>
<td>W1(T3)</td>
<td>V1(T2)</td>
</tr>
</tbody>
</table>

HIGH VOLS

LOW VOLS

AC Motor Connection Diagram

NINE LEADS

DUAL VOLTAGE-HIGH TO LOW VOLTAGE RATIO 2:1

WYE CONNECT

<table>
<thead>
<tr>
<th>U1(T1)</th>
<th>U2(T4)</th>
<th>V2(T5)</th>
</tr>
</thead>
<tbody>
<tr>
<td>W1(T3)</td>
<td>V1(T2)</td>
<td></td>
</tr>
</tbody>
</table>

LOW VOLS

HIGH VOLS

DELTA CONNECT

<table>
<thead>
<tr>
<th>U1(T1)</th>
<th>U2(T4)</th>
<th>V2(T5)</th>
</tr>
</thead>
<tbody>
<tr>
<td>W1(T3)</td>
<td>V1(T2)</td>
<td></td>
</tr>
</tbody>
</table>

AC Motor Connection Diagram

THREE PHASE

FOR SINGLE WINDING 3 PHASE MOTORS, LEAD MARKINGS CAN BE DIRECTLY TRANSLATED BETWEEN IEC AND NEMA DESIGNATIONS. FOR THESE MOTORS, THE LEAD MARKINGS ARE EQUIVALENT AS FOLLOWS.

U1-T1  U2-T4  U6-T7  U8-T10
V1-T2  V2-T5  V5-T8  V6-T11
W1-T3  W2-T6  W5-T9  W6-T12

EXAMPLES OF COMMON CONNECTIONS ARE GIVEN BELOW.

THREE LEADS

WYE CONNECT

<table>
<thead>
<tr>
<th>U1(T1)</th>
<th>U1(T1)</th>
<th>V1(T2)</th>
<th>W1(T3)</th>
</tr>
</thead>
</table>

Wiring Diagram

<table>
<thead>
<tr>
<th>LINE 1</th>
<th>LINE 2</th>
<th>LINE 3</th>
</tr>
</thead>
</table>

DELTA CONNECT

<table>
<thead>
<tr>
<th>U1(T1)</th>
<th>U1(T1)</th>
<th>V1(T2)</th>
</tr>
</thead>
</table>

Wiring Diagram

<table>
<thead>
<tr>
<th>LINE 1</th>
<th>LINE 2</th>
<th>LINE 3</th>
</tr>
</thead>
</table>
Connection Diagrams  Continued

AC Motor Connection Diagram

Twelve Leads

High Volts

U1(T1)
U2(T4)
U3(T7)
U4(T10)
U5(T13)
U6(T16)
V1(T2)
V2(T5)
V3(T8)
V4(T11)
V5(T14)
V6(T17)
W1(T3)
W2(T6)
W3(T9)
W4(T12)
W5(T15)
W6(T18)

Low Volts

W1(T3)
W2(T6)
W3(T9)
W4(T12)
W5(T15)
W6(T18)
V1(T2)
V2(T5)
V3(T8)
V4(T11)
V5(T14)
V6(T17)
U1(T1)
U2(T4)
U3(T7)
U4(T10)
U5(T13)
U6(T16)

Line 1

U1(T1)
U2(T4)
U3(T7)
U4(T10)

Line 2

U5(T13)
U6(T16)

Line 3

W1(T3)
W2(T6)
W3(T9)
W4(T12)
W5(T15)
W6(T18)

Start

U1(T1)
V1(T5)
W1(T9)

Run

U2(T4)
V2(T5)
W2(T8)

AC Motor Connection Diagram

Single Winding Multi-Speeds Constant HP

(T1) 1U

(T6) 2W

(T2) 1V

(T5) 2V

(T4) 2U

1W (T3)

2V (T5)

(T1) 1U

(T6) 2W

(T2) 1V

(T5) 2V

(T4) 2U

(N.P. 1634-DE)

DC Motor Connection Diagram

Wiring Diagram Type "T" Motor

(+)

A1(A1)
A2(B2)
S1(D1)
S2(D2)

Counter-clockwise Rotation

Rotation = Facing Commutator End

Comparision of IEC and NEMA Lead Markings

For Direct Current Motors

A1 → A1
A2 → B2
S1 → D1
S2 → D2

MOTOR WINDING THERMOSTATS

CONTACTS ____________________________ °C
FIGURE NUMBER _____________________

CONTACT RATING

VOLTS CONTINUOUS AMPERES INRUSH AMPERES

110 - 120 3.0 3.0

220 - 240 1.5 15

440 - 480 0.75 7.5

500 - 600 0.60 6.0

THERMOSTATS

NORMALLY CLOSED NORMALLY OPEN

FIGURE 1

P1

P2

FIGURE 2

P1

P2

FIGURE 3

P1

P2

FIGURE 4

P1

P2

FIGURE 5

P1

P2

FIGURE 6

P1

P2

MN408
Initial Lubrication

Baldor•Reliance motors are shipped from the factory with the bearings properly packed with grease and ready to operate. Where the unit has been subjected to extended storage (6 months or more) the bearings should be relubricated (regreasable type) prior to starting. When motors are equipped for oil mist lubrication refer to the instruction manual for installation, operation, and maintenance of oil mist lubrication systems.

Caution: Shaker Duty motors must be properly lubricated prior to Start Up to prevent damage. See Section 3.

First Time Start Up

Be sure that all power to motor and accessories is off. Be sure the motor shaft is disconnected from the load and will not cause mechanical rotation of the motor shaft.

1. Make sure that the mechanical installation is secure. All bolts and nuts are tightened etc.
2. If motor has been in storage or idle for some time, check winding insulation integrity.
3. Inspect all electrical connections for proper termination, clearance, mechanical strength and electrical continuity.
4. Be sure all shipping materials and braces (if used) are removed from motor shaft.
5. Manually rotate the motor shaft to ensure that it rotates freely.
6. Replace all panels and covers that were removed during installation.
7. Momentarily apply power and check the direction of rotation of the motor shaft.
8. If motor rotation is wrong, be sure power is off and change the motor lead connections. Verify rotation direction before you continue.
9. Start the motor and ensure operation is smooth without excessive vibration or noise. If so, run the motor for 1 hour with no load connected.
10. After 1 hour of operation, disconnect power and connect the load to the motor shaft. Verify all coupling guards and protective devices are installed. Ensure motor is properly ventilated.
11. If motor is totally enclosed fan−cooled or non−ventilated it is recommended that condensation drain plugs, if present, be removed. These are located in the lower portion of the end−shields. Totally enclosed fan−cooled “XT” motors are normally equipped with automatic drains which may be left in place as received.

**Coupled Start Up**

This procedure assumes a coupled start up. Also, that the first time start up procedure was successful.

1. Check the coupling and ensure that all guards and protective devices are installed.
2. Check that the coupling is properly aligned and not binding.
3. The first coupled start up should be with no load. Apply power and verify that the load is not transmitting excessive vibration back to the motor though the coupling or the foundation. Vibration should be at an acceptable level.
4. Run for approximately 1 hour with the driven equipment in an unloaded condition.

The equipment can now be loaded and operated within specified limits. Do not exceed the name plate ratings for amperes for steady continuous loads.

**Jogging and Repeated Starts**

Repeated starts and/or jogs of induction motors generally reduce the life of the motor winding insulation. A much greater amount of heat is produced by each acceleration or jog than by the same motor under full load. If it is necessary to repeatedly start or jog the motor, it is advisable to check the application with your local Baldor distributor or Baldor Service Center.

**Heating**

− Duty rating and maximum ambient temperature are stated on the motor name plate. Do not exceed these values. If there is any question regarding safe operation, contact your local Baldor distributor or Baldor Service Center.

**Hazardous Locations**

Hazardous locations are those where there is a risk of ignition or explosion due to the presence of combustible gases, vapors, dust, fibers or flyings.

**Selection**

Facilities requiring special equipment for hazardous locations are typically classified in accordance with local requirements. In the US market, guidance is provided by the National Electric Code. In international hazardous location areas, guidance for gas / vapor / mist classification is given in IEC60079−14, or for dust in IEC61241−14. This classification process lets the installer know what equipment is suitable for installation in that environment, and identifies what the maximum safe temperature or temperature class is required. It is the customer or users responsibility to determine the area classification and select proper equipment.

Areas are classified with respect to risk and exposure to the hazard. In the US market, areas are typically classified as follows Class, Division, Group and Temperature Class. In some newer installations in the US and in most international markets, areas are classified in Zones.

**Protection Concepts**

**Class I Division 1 / Zone 1 [Equipment Group I (mining) or II (surface), Equipment Protection Level (EPL) Gb, Mb]**

Baldor offers a range of motors suitable for installation in a Division 1 or Zone 1 environment. These motors are known as explosion proof or flameproof. Motors that are explosion proof or flameproof use specially machined flameproof joints between the end bell or bracket and the frame, as well as along the rotating shaft and at connection box covers and entries. The fit of these flameproof joints are designed to contain the combustion or quench the flame of an explosive gas atmosphere prior to it exiting the motor. These flameproof joints have lengths and widths selected and tested based on the gas group present in the atmosphere. Baldor•Reliance motors are typically designed to meet Class I (Division 1) Group C and D (explosion proof) or Ex d IIB (flameproof).

An application note regarding equipment applied in accordance with the US National Electric Code (NFPA 70−2008) − according to Article 500.8(C) Marking, sub clause (2) in the fine print note, it is noted that equipment not marked to indicate a division is suitable for both Division 1 and Division 2 locations. These motors are not gas tight. To the contrary, this protection concept assumes that due to the normal heating and cooling cycle of motor operation that any gas present will be drawn into the motor. Since flameproof or explosion proof motors are designed to contain the combustion and extinguish any flame transmission, for this protection concept, only external surface temperatures are of concern. Thermal limiting devices such as thermostats, thermistors or RTDs may be provided on these motors to limit the external surface temperature during overload conditions.

When explosion proof or flameproof motors are provided with intrinsically safe sensors, the integrity of that system relies upon the proper application and selection of barriers and cables as described in the sensor manufacturers control drawing. The control drawing will be shipped with the motor, and it is important that those instructions be provided to the equipment installer.
If thermostats are provided as a condition of certification, it is the installer's responsibility to make sure that these devices are properly connected to a suitable switching device. The ATEX directive requires that motor shutdown on thermal trip be accomplished without an intermediate software command. Where intermediate circuitry is involved the circuit shall fall within the scope of a safety, controlling and regulating device as defined in article 1(2) of European Directive 2014/34/EU, and shall be covered by an appropriate EC Type Examination Certificate.

Flameproof motors, internationally referred to as Ex d use a protection concept similar to that used in Class I Division 1 motors, with minor differences in the flameproof joints and cable entry designs. Flameproof and explosion proof motors are both type tested. Representative motors are connected to a reference gas and ignited in laboratory conditions to verify that the flame is not transmitted outside the motor enclosure and to determine the maximum internal pressure encountered.

Explosion proof and Flame proof motors shipped without a conduit box require use of a certified box of suitable dimensions and that is appropriate for the classification. Openings in connection boxes must be closed with suitably certified and dimensioned device.

Hazardous location motors equipped with NPT pipe nipples are designed and built such that the pipe nipple is securely attached to the motor frame. This is accomplished externally by interference between the threads as well as tack welding. The conduit box is securely attached to the pipe nipple at the factory per:

1. Standard Commercial NPT & Explosion Proof IEC/ATEX parts: L-1 gauging notch +/- 1 thread (ref. ANSI/ASME B1.20.1 and Clarification Sheet ExNB/98/06/010/CS) Note: Clarification Sheet ExNB/98/06/010/CS provides inspection criteria to meet (6 threads minimum per engineering part drawing for ATEX parts).

2. Explosion Proof UL conduit boxes & MSHA parts: L-1 gauging notch +1 min to +3 1/2 max threads. Note: Provides inspection criteria to meet (5 threads minimum per engineering part drawing for MSHA parts and meet UL 1203 requirement for L-1 gauging notch flush to +3 1/2 max threads).

This allows the end user to position the conduit box according to the application then secure when in place. For obvious reasons having the conduit box snug prior to affixing to the pipe nipple is preferable. However, the guidance in numbers 1 and 2 above can be used in determining thread engagement.

Note: In the United States most non-mining applications have rigid conduit for cabling, therefore not tack welding the conduit box to the pipe nipple is standard. In markets outside the United States, flexible conduit/cabling are common and end users should take note to secure the conduit box to the pipe nipple once in position. Further, the flexible leads should be secured to inhibit forces acting on the conduit box.

**Class I Division 2 / Zone 2 Ex nA, [Equipment Protection Level (EPL) Gc]**

This protection concept relies on having no sources of ignition present such as arcing parts or hot surfaces. For this protection concept, internal temperatures as well as external temperatures are considered. In many cases, the internal temperatures are higher than the external temperatures and therefore become the limiting factor in determination of temperature code designation. In these applications, it is very important to use a motor that has been evaluated thermally for use with an inverter or converter, if variable speed operation is desired. Thermostats used for Class I Division 2 and Ex nA motors are used to protect the motor only. For motors using flying lead construction, it is important to use connection lugs and insulate with heat shrink tubing or a double wrap of insulation grade electrical tape to avoid the risk of spark or ignition.

**Class II Division 1 / Zone 21 [Equipment Group III, Equipment Protection Level (EPL) Db]**

This area classification is one where the risk of ignitable concentrations of dust is present at all or some of the time. The protection concepts used for Class II Division 1 is similar to flamepath, except with additional dust exclusion paths designed for the rotating shaft. In the international designations, this concept is referred to as dust ignition proof or Ex tD. External surface temperature remains the limiting factor. Thermal limiting devices such as thermostats, thermistors or RTDs may be provided on these motors to limit the external surface temperature during overload conditions. If thermostats are provided as a condition of certification, it is the installer's responsibility to make sure that these devices are properly connected to a suitable switching device.

Note: In the North American area classification system, Class III exists for fibers and flyings. In the IEC designation, both dusts and flyings are absorbed into Group III.

**Class II Division 2 / Zone 22 [Equipment Group III, Equipment Protection Level (EPL) Dc]**

This area classification is one where the risk of exposure to ignitable concentrations of dust are not likely to occur under normal operating conditions and relies heavily on the housekeeping practices within the installation.

**Sine Wave Power Operation for Division 1 or 2 and Zone 1 or 2 and Zone 21 or 22 Hazardous Location.**

These motors are designed to operate at or below the maximum surface temperature (or T–Code) stated on the nameplate. Failure to operate the motor properly can cause this maximum surface temperature to be exceeded. If applied in a Division 1 or 2 / Zone 1 or 2 and Zone 21 or 22 environment, this excessive temperature may cause ignition of hazardous materials. Operating the motor at any of the following conditions can cause the marked surface temperature to be exceeded.
1. Motor load exceeding service factor nameplate value
2. Ambient temperatures above nameplate value
3. Voltages above or below nameplate value
4. Unbalanced voltages
5. Loss of proper ventilation
6. Altitude above 3300 feet / 1000 meters
7. Severe duty cycles of repeated starts
8. Motor stall
9. Motor reversing
10. Single phase operation of polyphase equipment
11. Variable frequency operation

**Variable Frequency Power Operation for Division 1 or 2 and Zone 1 or 2 and Zone 21 or 22**

Hazardous Location (motors with maximum surface temperature listed on the nameplate). Only motors with nameplates marked for use on inverter (variable frequency) power, and labeled for specific hazardous areas may be used in those hazardous areas on inverter power. The motor is designed to operate at or below the maximum surface temperature (or T-Code) stated on the nameplate. Failure to operate the motor properly can cause this maximum surface temperature to be exceeded.

If applied in a Division 1 or 2 / Zone 1 or 2 and Zone 21 or 22 environment, this excessive temperature may cause ignition of hazardous materials. Operating the motor at any of the following conditions can cause the marked surface temperature to be exceeded.
1. Motor load exceeding service factor nameplate value
2. Ambient temperature above nameplate value
3. Voltage (at each operating frequency) above or below rated nameplate value
4. Unbalanced voltages
5. Loss of proper ventilation
6. Operation outside of the nameplate speed / frequency range
7. Altitudes above 3300 feet / 1000 meters
8. Single phase operation of polyphase equipment
9. Unstable current wave forms
10. Lower than name plate minimum carrier frequency

**Thermal Limiting**

Thermal limiting devices are temperature sensing control components installed inside the motor to limit the internal temperature of the motor frame by interrupting the circuit of the holding coil of the magnetic switch or contactor. They are required for most Division 1 and Zone 1 applications. For Division 2 or Zone 2 applications, motors should be selected that preclude running temperatures from exceeding the ignition temperatures for the designated hazardous material. In Division 2 or Zone 2 classified locations, thermal limiting devices should only be used for winding protection and not considered for limiting all internal motor temperatures to specific ignition temperatures.

**Equipotential Bonding and Shaft Current Reduction**

Larger motors (ie WP construction) may require proper bonding between motor enclosures and covers to avoid the risk of stray currents during start up. Fastening methods and bonding straps must not be modified. Bearing currents can exist in some motors for both line–fed and inverter–fed applications. Larger line–fed motors may require at least one insulated bearing to prevent a flow of current through the bearings. Do not defeat such insulation whether the motor is line–fed or inverter–fed applications. Inverter–fed motors may require additional bearing insulation or even a shaft brush. Do not defeat such features. When the motor and the coupled load are not on a common conductive baseplate, it may also be necessary to electrically bond together the stationary parts of the motor and the coupled equipment.
Repair of Motors used in Hazardous Locations

Repair of hazardous certified motors requires additional information, skill, and care. It is the customer's responsibility to select service shops with proper qualifications to repair hazardous location motors. Contact the manufacturer for additional repair details. Use only original manufacturer's parts.

**Repair of Explosion Proof or Flame Proof Motors Class I Division 1 and Zone 1**

In the North American market, recertification programs are offered by Underwriters Laboratories and Canadian Standards Association which allow authorized service shops to mark the rebuilt motors as certified. In the international markets using IEC based requirements, repair should be undertaken only after consulting IEC60079–19 Explosive Atmospheres–Part 19 Equipment repair, overhaul and reclamation. If use of a certified repair facility is desired, consult the IECEX Repair Scheme at http://www.iecex.com/service_facilities.htm

Explosion proof and flameproof motors achieve their safety based on the mechanical construction – flameproof joints and bearing clearance, and the electrical design including any thermal limiting devices. If it is necessary to repair a flameproof or explosion proof motor, it is critical that the mechanical flameproof joints be maintained. Consult Baldor Electric Company for flameproof joint construction details.

Use only Baldor•Reliance supplied parts. Baldor does not recommend reclamation of parts. Since this protection method also relies on temperature being maintained, make sure that any rewinding uses the original electrical designs, including any thermal protection that may be present.

**Repair of Dust Ignition Proof Motors – Class II Division 1 and 2, Zone 21 and 22.**

For Dust Ignition Proof, proper sealing is required. Do not modify the motor construction to add any additional opening, and ensure that proper sealing is maintained in the connection box and at the shaft seal. Since this protection method also relies on temperature being maintained, make sure that any rewinding uses the original electrical designs, including any thermal protection that may be present.

**Repair of Class I Division 2 and Zone 2 motors**

For Division 2 and Zone 2, the internal and external temperatures are of concern. Since this protection method also relies on temperature being maintained, make sure that any rewinding uses the original electrical designs, including any thermal protection that may be present. Use only Baldor replacement thermostats, if provided.
WARNING: UL and EX Listed motors must only be serviced by UL or EX Approved Authorized Baldor Service Centers if these motors are to be returned to a hazardous and/or explosive atmosphere.

General Inspection
Inspect the motor at regular intervals, approximately every 500 hours of operation or every 3 months, whichever occurs first. Keep the motor clean and the ventilation openings clear. The following steps should be performed at each inspection:

WARNING: Do not touch electrical connections before you first ensure that power has been disconnected. Electrical shock can cause serious or fatal injury. Only qualified personnel should attempt the installation, operation and maintenance of this equipment.

1. Check that the motor is clean. Check that the interior and exterior of the motor is free of dirt, oil, grease, water, etc. Oily vapor, paper pulp, textile lint, etc. can accumulate and block motor ventilation. If the motor is not properly ventilated, overheating can occur and cause early motor failure.
2. Perform a dielectric with stand test periodically to ensure that the integrity of the winding insulation has been maintained. Record the readings. Immediately investigate any significant decrease in insulation resistance.
3. Check all electrical connectors to be sure that they are tight.

Relubrication & Bearings
Bearing grease will lose its lubricating ability over time, not suddenly. The lubricating ability of a grease (over time) depends primarily on the type of grease, the size of the bearing, the speed at which the bearing operates and the severity of the operating conditions. Good results can be obtained if the following recommendations are used in your maintenance program.

Type of Grease
A high grade ball or roller bearing grease should be used. Baldor motors are pregreased, normally with Polyrex EM (Exxon Mobil) or as stated on the nameplate. Do not mix greases unless compatibility has been checked and verified.

Ball Bearing Motors
Operating Temperature –25 °C (−15 °F) to 50 °C (120 °F)
- Exxon POLYREX EM (Standard on Baldor motors)
- Exxon UNIREX N2
- Exxon BEACON 325
- Chevron Oil SRI NO. 2 (Compatible with Polyrex EM)
- Chevron Oil BLACK PEARL
- Texaco, Inc. PREMIUM RB
- Texaco, Inc. POLYSTAR
- Amoco RYKON # 2
- Pennzoil PENNZLUBE EM−2
- Darmex DARMEX 707
- Darmex DARMEX 711
- Petro–Canada PEERLESS LLG
- Shell Oil DOLIUM BRB
Minimum Starting Temperature –60 °C (−76 °F)
- Shell Oil Co. AEROSHELL 7 (Standard on Baldor motors)
- Mobil MOBIL 28
- Mobil MOBILITH SHC 100 (Low Temperature – Arctic Duty)

Roller Bearing Motors
Operating Temperature –25 °C (−15 °F) to 50 °C (120 °F)
- Texaco, Inc. PREMIUM RB
- Mobil MOBILITH SHC 220 (Standard on Baldor motors)
- Chevron Oil BLACK PEARL
Relubrication Intervals

Recommended relubrication intervals are shown in Table 3-1. It is important to realize that the recommended intervals of Table 3-2 are based on average use.

Refer to additional information contained in Tables 3-2, 3-3 and 3-4.

Table 3-1 Relubrication Intervals *

<table>
<thead>
<tr>
<th>NEMA / (IEC) Frame Size</th>
<th>Rated Speed - RPM</th>
<th>10000</th>
<th>6000</th>
<th>3600</th>
<th>1800</th>
<th>1200</th>
<th>900</th>
</tr>
</thead>
<tbody>
<tr>
<td>Up to 210 incl. (132)</td>
<td>**</td>
<td>2700 Hrs.</td>
<td>5500 Hrs.</td>
<td>12000 Hrs.</td>
<td>18000 Hrs.</td>
<td>22000 Hrs.</td>
<td></td>
</tr>
<tr>
<td>Over 210 to 280 incl. (180)</td>
<td>**</td>
<td>3600 Hrs.</td>
<td>9500 Hrs.</td>
<td>15000 Hrs.</td>
<td>18000 Hrs.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Over 280 to 360 incl. (225)</td>
<td>**</td>
<td>* 2200 Hrs.</td>
<td>7400 Hrs.</td>
<td>12000 Hrs.</td>
<td>15000 Hrs.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Over 360 to 449 incl. (315)</td>
<td>**</td>
<td>*2200 Hrs.</td>
<td>3500 Hrs.</td>
<td>7400 Hrs.</td>
<td>10500 Hrs.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

* Relubrication intervals are for ball bearings.
For vertically mounted motors and roller bearings, divide the relubrication interval by 2.

** For motors operating at speeds greater than 3600 RPM, contact Baldor for relubrication recommendations.

Table 3-2 Service Conditions

<table>
<thead>
<tr>
<th>Severity of Service</th>
<th>Hours per day of Operation</th>
<th>Ambient Temperature Maximum</th>
<th>Atmospheric Contamination</th>
</tr>
</thead>
<tbody>
<tr>
<td>Standard</td>
<td>8</td>
<td>40 °C</td>
<td>Clean, Little Corrosion</td>
</tr>
<tr>
<td>Severe</td>
<td>16 Plus</td>
<td>50 °C</td>
<td>Moderate dirt, Corrosion</td>
</tr>
<tr>
<td>Extreme</td>
<td>16 Plus</td>
<td>&gt;50 °C* or Class H Insulation</td>
<td>Severe dirt, Abrasive dust, Corrosion, Heavy Shock or Vibration</td>
</tr>
<tr>
<td>Low Temperature</td>
<td>&lt;-29 °C</td>
<td></td>
<td>Special high temperature grease is recommended (Dow Corning DC44). Note that Dow Corning DC44 grease does not mix with other grease types. Thoroughly clean bearing &amp; cavity before adding grease.</td>
</tr>
</tbody>
</table>

** Special low temperature grease is recommended (Aeroshell 7).

Table 3-3 Relubrication Interval Multiplier

<table>
<thead>
<tr>
<th>Severity of Service</th>
<th>Multiplier</th>
</tr>
</thead>
<tbody>
<tr>
<td>Standard</td>
<td>1.0</td>
</tr>
<tr>
<td>Severe</td>
<td>0.5</td>
</tr>
<tr>
<td>Extreme</td>
<td>0.1</td>
</tr>
<tr>
<td>Low Temperature</td>
<td>1.0</td>
</tr>
</tbody>
</table>

Some motor designs use different bearings on each motor end. This is normally indicated on the motor nameplate. In this case, the larger bearing is installed on the motor Drive endplate. For best relubrication results, only use the appropriate amount of grease for each bearing size (not the same for both).
Table 3-4  Bearings Sizes and Types

<table>
<thead>
<tr>
<th>Frame Size NEMA (IEC)</th>
<th>Bearing Description (These are the “Large” bearings (Shaft End) in each frame size)</th>
<th>Weight of Grease to add * oz (Grams)</th>
<th>Volume of grease to be added</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>in³</td>
<td>teaspoon</td>
</tr>
<tr>
<td>56 to 140 (90)</td>
<td>6203</td>
<td>0.08 (2.4)</td>
<td>0.15</td>
</tr>
<tr>
<td>140 (90)</td>
<td>6205</td>
<td>0.15 (3.9)</td>
<td>0.2</td>
</tr>
<tr>
<td>180 (100–112)</td>
<td>6206</td>
<td>0.19 (5.0)</td>
<td>0.3</td>
</tr>
<tr>
<td>210 (132)</td>
<td>6307</td>
<td>0.30 (8.4)</td>
<td>0.6</td>
</tr>
<tr>
<td>250 (160)</td>
<td>6309</td>
<td>0.47 (12.5)</td>
<td>0.7</td>
</tr>
<tr>
<td>280 (180)</td>
<td>6311</td>
<td>0.61 (17)</td>
<td>1.2</td>
</tr>
<tr>
<td>320 (200)</td>
<td>6312</td>
<td>0.76 (20.1)</td>
<td>1.2</td>
</tr>
<tr>
<td>360 (225)</td>
<td>6313</td>
<td>0.81 (23)</td>
<td>1.5</td>
</tr>
<tr>
<td>400 (250)</td>
<td>6316</td>
<td>1.25 (33)</td>
<td>2.0</td>
</tr>
<tr>
<td>440 (280)</td>
<td>6318</td>
<td>1.52 (40)</td>
<td>2.5</td>
</tr>
<tr>
<td>440 (280)</td>
<td>6319</td>
<td>2.12 (60)</td>
<td>4.1</td>
</tr>
<tr>
<td>5000 to 5800 (315−355)</td>
<td>6328</td>
<td>4.70 (130)</td>
<td>9.2</td>
</tr>
<tr>
<td>5000 to 5800 (315−355)</td>
<td>NU328</td>
<td>4.70 (130)</td>
<td>9.2</td>
</tr>
<tr>
<td>360 to 449 (225–280)</td>
<td>NU319</td>
<td>2.12 (60)</td>
<td>4.1</td>
</tr>
<tr>
<td>AC Induction Servo</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>76 Frame 180 (112)</td>
<td>6207</td>
<td>0.22 (6.1)</td>
<td>0.44</td>
</tr>
<tr>
<td>77 Frame 210 (132)</td>
<td>6210</td>
<td>0.32 (9.0)</td>
<td>0.64</td>
</tr>
<tr>
<td>80 Frame 250(160)</td>
<td>6213</td>
<td>0.49 (14.0)</td>
<td>0.99</td>
</tr>
</tbody>
</table>

* Weight in grams = .005 DB  of grease to be added

Note: Not all bearing sizes are listed. For intermediate bearing sizes, use the grease volume for the next larger size bearing.

Caution:  To avoid damage to motor bearings, grease must be kept free of dirt. For an extremely dirty environment, contact your Baldor distributor or an authorized Baldor Service Center for additional information.

Relubrication Procedure  Be sure that the grease you are adding to the motor is compatible with the grease already in the motor. Consult your Baldor distributor or an authorized service center if a grease other than the recommended type is to be used.

Caution:  Do not over–lubricate motor as this may cause premature bearing failure.

With Grease Outlet Plug
1. With the motor stopped, clean all grease fittings with a clean cloth.
2. Remove grease outlet plug.

Caution:  Over–lubricating can cause excessive bearing temperatures, premature lubrication breakdown and bearing failure.
3. Add the recommended amount of grease.
4. Operate the motor for 15 minutes with grease plug removed. This allows excess grease to purge.
5. Re-install grease outlet plug.
Without Grease Provisions

Note: Only a Baldor authorized and UL or CSA certified service center can disassemble a UL/CSA listed explosion proof motor to maintain it’s UL/CSA listing.

1. Disassemble the motor.
2. Add recommended amount of grease to bearing and bearing cavity. (Bearing should be about 1/3 full of grease and outboard bearing cavity should be about 1/2 full of grease.)
3. Assemble the motor.

Sample Relubrication Determination

Assume - NEMA 286T (IEC 180), 1750 RPM motor driving an exhaust fan in an ambient temperature of 43 ºC and the atmosphere is moderately corrosive.

1. Table 3-2 list 9500 hours for standard conditions.
2. Table 3-3 classifies severity of service as “Severe”.
3. Table 3-5 shows that 1.2 in³ or 3.9 teaspoon of grease is to be added.

Note: Smaller bearings in size category may require reduced amounts of grease.

Shaker Duty Motors only

Caution: Shaker Duty motors must be properly lubricated prior to Start Up to prevent damage. See Table 3-6.

Lubrication should be performed before Start Up and at regular maintenance intervals. Follow these recommendations to ensure proper lubrication.

Recommended Lubricant

For ambient temperatures between −15 ºF to 120 ºF the following lubricants are recommended: Mobil PolyrexEM, Texaco Premium RB, Exxon Unirex N−2.

Do not mix greases unless compatibility has been checked and verified.

<table>
<thead>
<tr>
<th>NEMA Frame Size</th>
<th>Normal Duty</th>
<th>Severe Duty</th>
<th>Extreme Duty</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Start Up</td>
<td>Relub</td>
<td>Start Up</td>
</tr>
<tr>
<td>184TY</td>
<td>1.4</td>
<td>0.5</td>
<td>1.4</td>
</tr>
<tr>
<td>215TY</td>
<td>1.6</td>
<td>0.5</td>
<td>1.6</td>
</tr>
<tr>
<td>256TY</td>
<td>7</td>
<td>1</td>
<td>11</td>
</tr>
<tr>
<td>286TY</td>
<td>9</td>
<td>1</td>
<td>15</td>
</tr>
</tbody>
</table>

Lubrication Frequency

Normal Duty 8 hours per day (16 hours per day in a clean environment), Lubricate every 2 months.

Severe Duty 16 hours per day or more in a dirty environment (corrosive atmosphere, chemical fumes, acids, alkalis or extreme high humidity). Lubricate every month or 700 hours of operation.

Extreme Duty operation in extremely dirty or dusty environments and high ambient temperatures exceeding 104 ºF (40 ºC). Lubricate twice a month or 350 hours of operation.

Lubrication Procedure

1. Locate the grease inlet and outlet. Clean the areas.
2. Remove the plug(s) and install a grease fitting in the inlet if grease fitting is not already installed.
3. Add the recommended amount of lubricant.
4. Run the motor for two hours with the outlet plug removed.
5. Install outlet plug.

Note: To loosen hardened grease it may be necessary to insert a rod or wire into the grease inlet and outlet holes.
<table>
<thead>
<tr>
<th>Symptom</th>
<th>Possible Causes</th>
<th>Possible Solutions</th>
</tr>
</thead>
<tbody>
<tr>
<td>Motor will not start</td>
<td>Usually caused by line trouble, such as, single phasing at the starter.</td>
<td>Check source of power. Check overloads, fuses, controls, etc.</td>
</tr>
<tr>
<td>Excessive humming</td>
<td>High Voltage. Eccentric air gap.</td>
<td>Check input line connections. Have motor serviced at local Baldor service center.</td>
</tr>
<tr>
<td>Motor Over Heating</td>
<td>Overload. Compare actual amps (measured) with nameplate rating.</td>
<td>Locate and remove source of excessive friction in motor or load. Reduce load or replace with motor of greater capacity.</td>
</tr>
<tr>
<td></td>
<td>Single Phasing.</td>
<td>Check current at all phases (should be approximately equal) to isolate and correct the problem.</td>
</tr>
<tr>
<td></td>
<td>Improper ventilation.</td>
<td>Check external cooling fan to be sure air is moving properly across cooling fins. Excessive dirt build-up on motor. Clean motor.</td>
</tr>
<tr>
<td></td>
<td>Unbalanced voltage.</td>
<td>Check voltage at all phases (should be approximately equal) to isolate and correct the problem.</td>
</tr>
<tr>
<td></td>
<td>Rotor rubbing on stator.</td>
<td>Check air gap clearance and bearings. Tighten &quot;Thru Bolts&quot;.</td>
</tr>
<tr>
<td></td>
<td>Over voltage or under voltage.</td>
<td>Check input voltage at each phase to motor.</td>
</tr>
<tr>
<td></td>
<td>Open stator winding.</td>
<td>Check stator resistance at all three phases for balance.</td>
</tr>
<tr>
<td></td>
<td>Grounded winding.</td>
<td>Perform dielectric test and repair as required.</td>
</tr>
<tr>
<td></td>
<td>Improper connections.</td>
<td>Inspect all electrical connections for proper termination, clearance, mechanical strength and electrical continuity. Refer to motor lead connection diagram.</td>
</tr>
<tr>
<td>Bearing Over Heating</td>
<td>Misalignment.</td>
<td>Check and align motor and driven equipment.</td>
</tr>
<tr>
<td></td>
<td>Excessive belt tension.</td>
<td>Reduce belt tension to proper point for load.</td>
</tr>
<tr>
<td></td>
<td>Excessive end thrust.</td>
<td>Reduce the end thrust from driven machine.</td>
</tr>
<tr>
<td></td>
<td>Excessive grease in bearing.</td>
<td>Remove grease until cavity is approximately 3/4 filled.</td>
</tr>
<tr>
<td></td>
<td>Insufficient grease in bearing.</td>
<td>Add grease until cavity is approximately 3/4 filled.</td>
</tr>
<tr>
<td></td>
<td>Dirt in bearing.</td>
<td>Clean bearing cavity and bearing. Repack with correct grease until cavity is approximately 3/4 filled.</td>
</tr>
<tr>
<td>Vibration</td>
<td>Misalignment.</td>
<td>Check and align motor and driven equipment.</td>
</tr>
<tr>
<td></td>
<td>Rubbing between rotating parts and stationary parts.</td>
<td>Isolate and eliminate cause of rubbing.</td>
</tr>
<tr>
<td></td>
<td>Rotor out of balance.</td>
<td>Have rotor balance checked are repaired at your Baldor Service Center.</td>
</tr>
<tr>
<td></td>
<td>Resonance.</td>
<td>Tune system or contact your Baldor Service Center for assistance.</td>
</tr>
<tr>
<td>Noise</td>
<td>Foreign material in air gap or ventilation openings.</td>
<td>Remove rotor and foreign material. Reinstall rotor. Check insulation integrity. Clean ventilation openings.</td>
</tr>
<tr>
<td>Growling or whining</td>
<td>Bad bearing.</td>
<td>Replace bearing. Clean all grease from cavity and new bearing. Repack with correct grease until cavity is approximately 3/4 filled.</td>
</tr>
</tbody>
</table>
Suggested bearing and winding RTD setting guidelines for Non−Hazardous Locations ONLY

Most large frame AC Baldor motors with a 1.15 service factor are designed to operate below a Class B (80 °C) temperature rise at rated load and are built with a Class H winding insulation system. Based on this low temperature rise, RTD (Resistance Temperature Detectors) settings for Class B rise should be used as a starting point. Some motors with 1.0 service factor have Class F temperature rise.

The following tables show the suggested alarm and trip settings for RTDs. Proper bearing and winding RTD alarm and trip settings should be selected based on these tables unless otherwise specified for specific applications.

If the driven load is found to operate well below the initial temperature settings under normal conditions, the alarm and trip settings may be reduced so that an abnormal machine load will be identified.

The temperature limits are based on the installation of the winding RTDs imbedded in the winding as specified by NEMA. Bearing RTDs should be installed so they are in contact with the outer race on ball or roller bearings or in direct contact with the sleeve bearing shell.

Table 3-7  Winding RTDs – Temperature Limit In °C (40 °C Maximum Ambient)

<table>
<thead>
<tr>
<th>Motor Load (Typical Design)</th>
<th>Class B Temp Rise ≤ 80 ºC Alarm</th>
<th>Trip</th>
<th>Class F Temp Rise ≤ 105 ºC Alarm</th>
<th>Trip</th>
<th>Class H Temp Rise ≤ 125 ºC Alarm</th>
<th>Trip</th>
</tr>
</thead>
<tbody>
<tr>
<td>≤ Rated Load</td>
<td>130</td>
<td>140</td>
<td>155</td>
<td>160</td>
<td>165</td>
<td>175</td>
</tr>
<tr>
<td>Rated Load to 1.15 S.F.</td>
<td>140</td>
<td>150</td>
<td>160</td>
<td>165</td>
<td>180</td>
<td>185</td>
</tr>
</tbody>
</table>

Note: • Winding RTDs are factory production installed, not from Mod–Express.

When Class H temperatures are used, consider bearing temperatures and relubrication requirements.

Table 3-8  Bearing RTDs – Temperature Limit In °C (40 °C Maximum Ambient)

<table>
<thead>
<tr>
<th>Bearing Type</th>
<th>Oil or Grease</th>
<th>Anti–Friction</th>
<th>Sleeve</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Alarm</td>
<td>Trip</td>
</tr>
<tr>
<td>Standard*</td>
<td></td>
<td>95</td>
<td>100</td>
</tr>
<tr>
<td>High Temperature**</td>
<td></td>
<td>110</td>
<td>115</td>
</tr>
</tbody>
</table>

Notes: * Bearing temperature limits are for standard design motors operating at Class B temperature rise.

** High temperature lubricants include some special synthetic oils and greases.

Greases that may be substituted that are compatible with Polyrex EM (but considered as “standard” lubricants include the following:

- Texaco Polystar
- Mobilith SHC−100
- Darmex 707

- Rykon Premium #2
- Pennzoil Pennzube EM−2
- Darmex 711

- Chevron SRI #2
- Chevron Black Pearl
- Petro–Canada Peerless LLG

See the motor nameplate for replacement grease or oil recommendation.

Contact Baldor application engineering for special lubricants or further clarifications.